Bot initially at Manual Start Zone.

1. MS Zone -> Loading Zone via wall following.
2. Attach with Rack(A).
3. Loading Zone -> TZ1
4. Signal Autonomous Throw Successful
5. Get back to make space for autonomous.
6. Move to TZ2
7. Signal throw successful
8. TZ2 -> Loading Zone. (Rotate while moving to align bot. After rotation, wall following)
9. Attach with Rack(B)
10. Move to TZ2
11. Transfer Rack to Autonomous.